

aUtomaTed Open Precision fArming Platform

Dennis Kooijman

Intelligent Autonomous Mobility Center (NL)



This project has received funding from the European Union's Horizon 2020 research and innovation programme under grand agreement no 862665 ICT-AGRI-FOOD.





- Take advantage of the commonality of different next-gen smart farming applications when you combine them.
- 'Digital twin'
- Multiple devices can use the same data
- Eases the effort to obain contextual information and aid precision farming.



HORIZON 2020

This project has received funding from the European Union's Horizon 2020 research and innovation programme under grand agreement no 862665 ICT-AGRI-FOOD.



Goal

Support the mass-adoption of data-rich, small interval precision-farming, while limiting the resulting increase of labor & expertise related to:

- manual/automated robotic & agri-equipment operation
- fusion of the heterogeneous multi-device data





Project



Seaweed use-case (North-Sea)



Vineyard use-case (Turkey)



GIS + Robotics

... in a low-bandwith environment



Demo / Evaluation; Collaborative <u>autonomous</u> driving, flying or sailing for yield estimation.

USE-CASE & STAKEHOLDER INPUT

FRAMEWORK DEVELOPMENT

EVALUATION & DEMONSTRATION



This project has received funding from the European Union's Horizon 2020 research and innovation programme under grand agreement no 862665 ICT-AGRI-FOOD.